

Autonics

PULSE METER MP5W SERIES

M A N U A L



Thank you very much for selecting Autonics products.
For your safety, please read the following before using.

Caution for your safety

- ※Please keep these instructions and review them before using this unit.
- ※Please observe the cautions that follow;
- Warning** Serious injury may result if instructions are not followed.
- Caution** Product may be damaged, or injury may result if instructions are not followed.
- ※The following is an explanation of the symbols used in the operation manual.
- ⚠caution: Injury or danger may occur under special conditions.

Warning

- In case of using this unit with machineries(Nuclear power control, medical equipment, vehicle, train, airplane, combustion apparatus, entertainment or safety device etc), it requires installing fail-safe device, or contact us for information on type required.**
It may result in serious damage, fire or human injury.
- It must be mounted on panel.**
It may give an electric shock.
- Do not repair or check up when power on.**
It may give an electric shock.
- Do not disassemble and modify this unit, when it requires. If needs, please contact us.**
It may give an electric shock and cause a fire.
- Please check the number of terminal when connect power line or measuring input.**
It may cause a fire.

Caution

- This unit shall not be used outdoors.**
It might shorten the life cycle of the product or give an electric shock.
- When wire connection for power input and measuring input, the tightening strength for screw bolt on terminal block should be over than 0.74N · m ~ 0.90N · m.**
It may result in malfunction or fire due to contact failure.
- Please observe specification rating.**
It might shorten the life cycle of the product and cause a fire.
- Do not use the load beyond rated switching capacity of Relay contact.**
It may cause insulation failure, contact melt, contact failure, relay broken, fire etc.
- In cleaning the unit, do not use water or an oil-based detergent.**
It might cause an electric shock or fire that will result in damage to this product.
- Do not use this unit at place where there are flammable or explosive gas, humidity, direct ray the sun, radiant heat, vibration, impact etc.**
It may cause a fire or explosion.
- Do not inflow dust or wire dregs into inside of this unit.**
It may cause a fire or mechanical trouble.
- Please connect properly after checking the polarity of measuring terminals.**
It may cause a fire or explosion.

※The above specification are changeable without notice anytime.

Ordering information

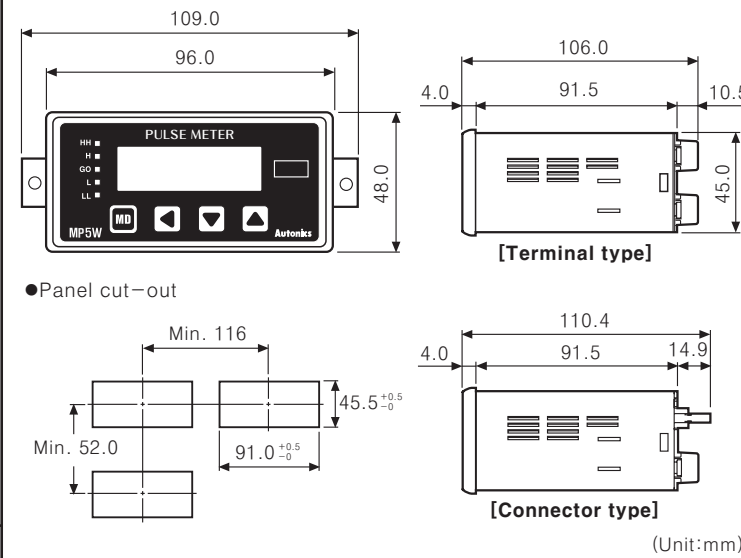
①Series	MP	Pulse meter
②Digit	5	5Digit(99999)
③Size	W	DIN Size W96 × H48mm
④Power supply	4	100-240VAC 50/60Hz
⑤Output (Main output +Sub output)		
Symbol	Main output(Comparative value output)	Sub output(Display value output)
N	Indication type only	X
A	Relay five-stage(HH, H, GO, L, LL)	X
1	Relay three-stage(H, GO, L)	X
2	NPN open collector five-stage output	BCD Dynamic output
3	PNP open collector five-stage output	BCD Dynamic output
4	NPN open collector five-stage output	PV retransmission(4-20mADC) output
5	PNP open collector five-stage output	PV retransmission(4-20mADC) output
6	NPN open collector five-stage output	Low speed serial output
7	PNP open collector five-stage output	Low speed serial output
8	NPN open collector five-stage output	RS485 communication output
9	PNP open collector five-stage output	RS485 communication output

※PNP open collector output:Option

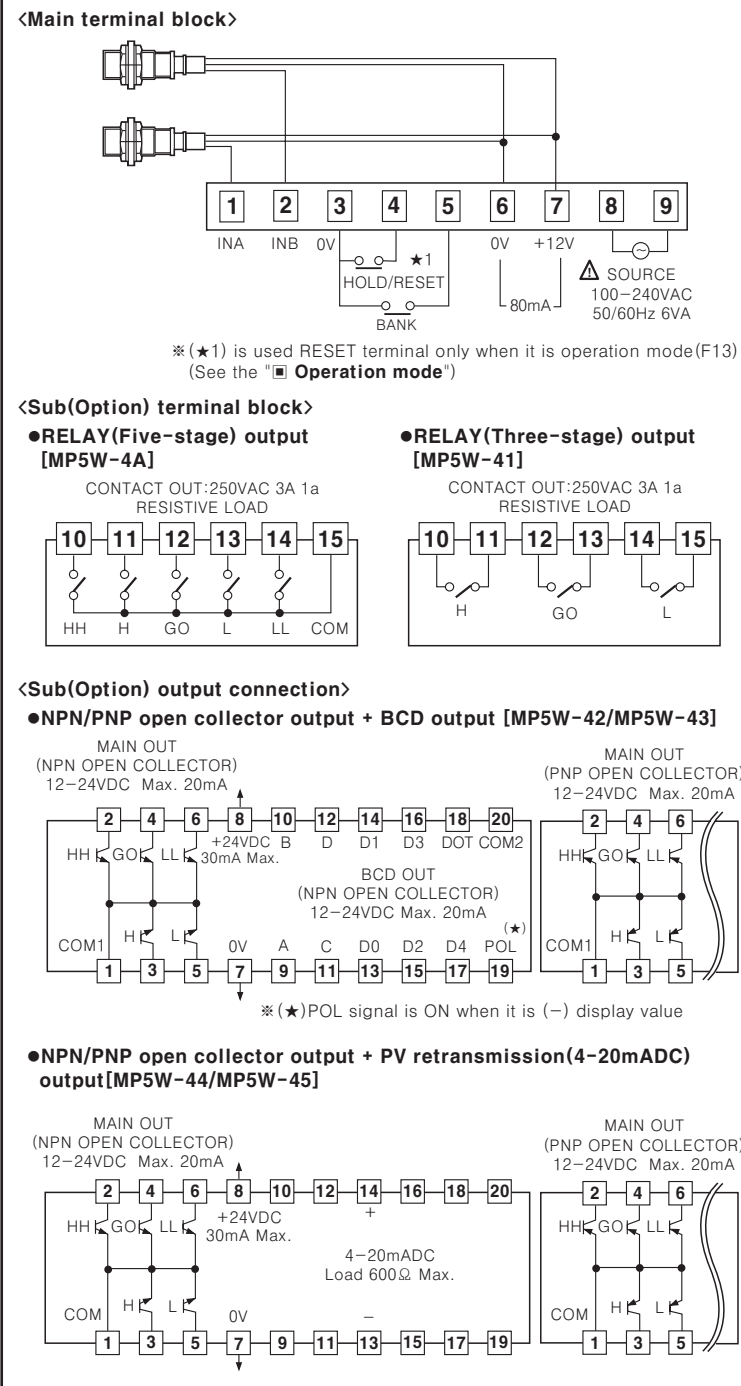
Specifications

Model	MP5W	
Power supply	100-240VAC 50/60Hz	
Allowable voltage range	90 to 110% of rated voltage	
Power consumption	Approx. Max. 6VA	
Power for external sensor	12VDC ±10%, 80mA	
Measuring accuracy (23 ±5°C)	• Mode F1, F4, F7, F8, F9, F10 : F.S. ±0.05% rdg ±1Digit • Mode F2, F3, F5, F6 : F.S. ±0.01% rdg ±1Digit	
Measuring range	• Mode F1, F4, F7, F8, F9, F10 : 0.0005Hz to 50kHz • Mode F3 : 0.02s to 3,200s • Mode F2, F5, F6 : 0.01s to 3,200s • Mode F11, F12, F13 : 0 to 4 × 10 ⁹ Count	
Input frequency	• Solid state input : Max. 50kHz(Pulse width:Min. 10μs) • Contact input : Max. 45Hz(Pulse width:Min. 11ms)	
Input level	[Voltage input] High : 4.5-24VDC, Low : 0-1VDC, Input impedance : 4.5kΩ [No-voltage input] Short-circuit impedance : Max. 300Ω, Residual voltage : Max. 1V, Open-circuit impedance : Min. 100kΩ	
Max. indication	5digit(-19999 to 99999)	
Display method	7 Segment LED(Zero Blanking)	
Display accuracy	0.05 / 0.5 / 1 / 2 / 4 / 8sec.(The same as update output cycle)	
Operation mode	Number of revolution/Speed/Frequency(F1), Passing speed(F2), Cycle(F3), Passing time(F4), Time width(F5), Time difference(F6), Absolute rate(F7), Error ratio(F8), Density(F9), Error(F10), Length measurement(F11), Interval(F12), Integration(F13)	
Prescale function	Direct input method(0.0001 × 10 ⁻⁹ to 9.9999 × 10 ⁹)	
Hysteresis	0 to 9999	
Other functions	• Lock setting function • Monitoring delay function • Auto-Zero time setting function • Monitoring function : Memorize max. value or min. value • Current output range selection(Current output type only) • Remote/Local switching function(Communication output type only) • Comparative output function(HH, H, GO, L, LL) • Data Bank switching function • Time unit selection function • Memory retention function(Mode F13 applied only) • Deviation memory function(F output mode applied only) ※Please see the last page for the detail.	
Output form	• Relay contact output(Three-stage output:3A) (Five-stage output:5A contact):Comparative output, Alarm output • Transistor output(NPN/PNP open collector) :Comparative output, Alarm output • Low speed serial output:Display value output • BCD Dynamic output:Display value output • PV retransmission output(4-20mADC):Display value output • RS485 communication output(32 channel) :Display value output, Comparative output, PC setting function	
Memory	Non-volatile memory(Input times : 100,000 times)	
Insulation resistance	Min. 100MΩ(Standard 500VDC) between terminal and case	
Dielectric strength	2000VAC 60Hz 1minute(Between terminals of AC power and case, Between terminals of AC power and measuring terminals)	
Impulse noise strength	±2000V the square wave noise(pulse width:1μs) by the noise simulator	
Vibration	Mechanical	0.75mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 2 hour
	Malfunction	0.5mm amplitude at frequency of 10 to 55Hz in each of X, Y, Z directions for 10 minutes
Shock	Mechanical	300m/s ² (Approx. 30G) 3 times at X, Y, Z direction
	Malfunction	100m/s ² (Approx. 10G) 3 times at X, Y, Z direction
Relay life cycle	Mechanical	Min.10,000,000 times
	Electrical	Min.100,000 times(250VAC 3A resistive load)
Ambient temperature		-10 to 50°C(at non-freezing status)[]
Storage temperature		-20 to 60°C(at non-freezing status)[]
Ambient humidity		35 to 85%RH
Weight		Approx. 230g

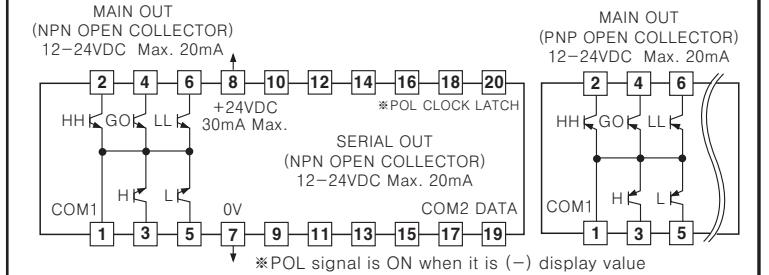
Dimensions



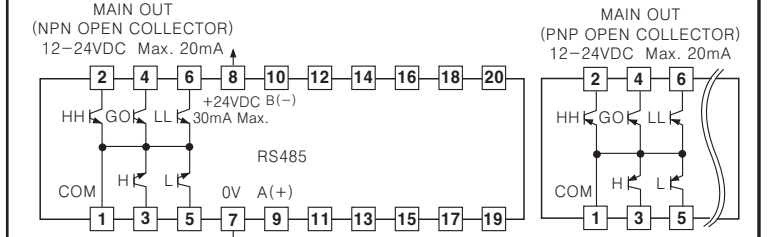
Connections



NPN/PNP open collector output + Low speed serial output [MP5W-46/MP5W-47]



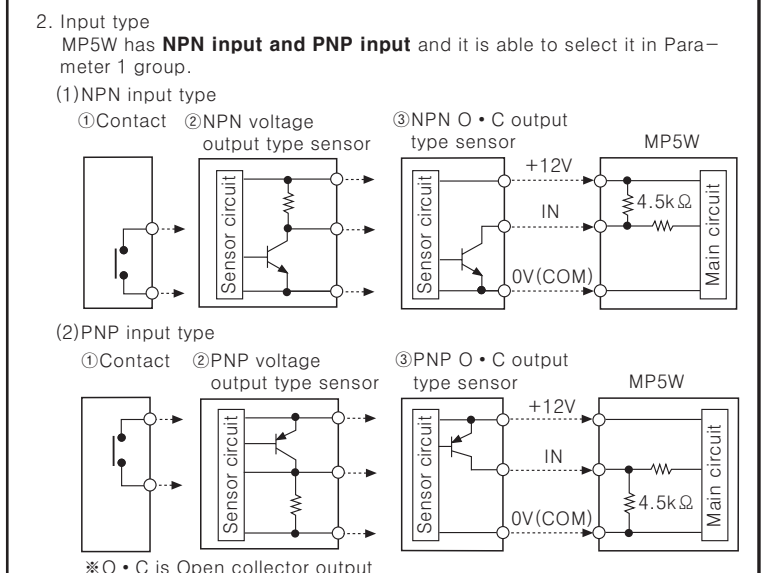
NPN /PNP open collector output + RS485 communication output [MP5W-48/MP5W-49]



Input · Output

Input specification

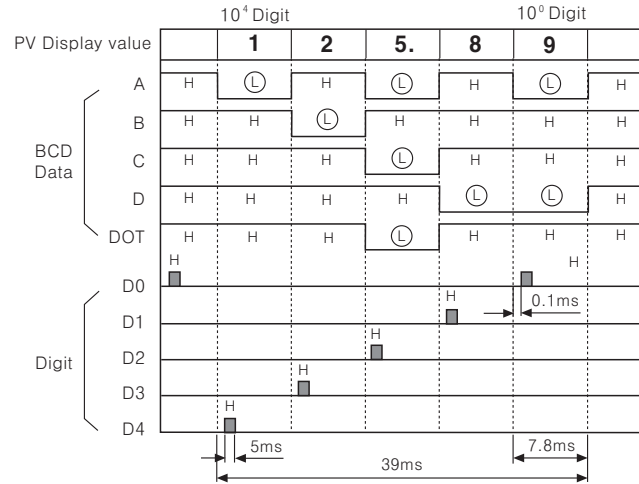
- Input signal
 - Solid state input
 - Input frequency: 50kHz(Max.)
But, standard duty rate of input signal is 1:1, ON/OFF pulse width should be each over 10μs.
 - Input voltage Level : ON voltage → 4.5-24V, OFF voltage → 0-1.0V
 - Relay contact input
 - Input frequency : 45Hz(Max.)
But, ON/OFF pulse width should be each over 11ms.
 - Relay contact specification : Please use a contact that can switch reliably at 12VDC, 2mA min. of load current.
- Input type
MP5W has **NPN input and PNP input** and it is able to select it in Parameter 1 group.
 - NPN input type
 - Contact
 - NPN voltage output type sensor
 - NPN O · C output type sensor
 - PNP input type
 - Contact
 - PNP voltage output type sensor
 - PNP O · C output type sensor



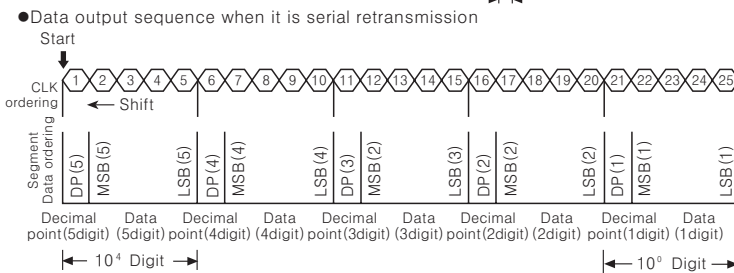
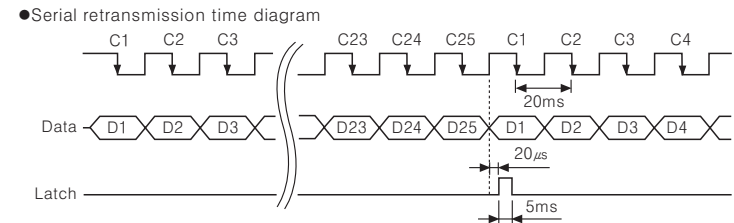
Output specification

- Relay output
 - Output : Comparative or alarm output(See the "Output mode")
 - Output method : Relay
 - Contact capacity : 250VAC 3A resistive load
 - Life cycle : Mechanical-20million times(Switch times 180 times/min.)
Electrical-Min.100,000 times(3A 250VAC, 30VDC at resistive load)(Switch times : 20 times/min.)
- TR output
 - Output : Comparative or alarm output(See the "Output mode")
 - Output method : NPN / PNP Open collector
 - Rated load voltage : 12-24VDC
 - Max. load current : 20mA

3. BCD Dynamic output
- Output : Display value
 - Output signal : BCD Data(A, B, C, D) ← A : Lowest bit, D : Highest bit
Digit Data(D0, D1, D2, D3, D4) ← D0 : Lowest digit, D4 : Highest digit
 - Output type : NPN Open Collector
 - Rated load voltage : 12-24VDC
 - Max. load current : 20mA
- Ex) When display value is 125.89

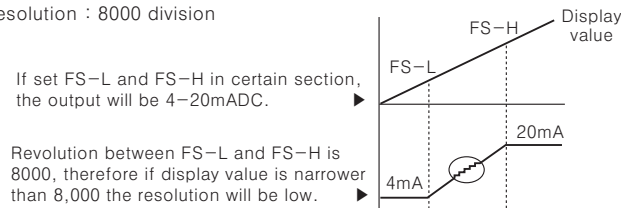


4. Low speed serial output
- Output : Display value
 - Output signal : CLK, Data, Latch
 - CLK cycle : 50Hz
 - Output CLK bit : 25 bit
 - Output Data bit : 25 bit
 - Output form: NPN Open Collector
 - Rated load voltage : 12-24VDC
 - Max. load current : 20mA



5. PV retransmission output(4-20mADC)

- Application : To transmit the measured value
- Function : This function is to transmit 4-20mADC converted from measured display value between High limit output(FS-H) and Low limit(FS-L).
- Range of High/Low limit output setting
 - High limit setting range(FS-H): From min. to max within range of measurement
 - Low limit setting range(FS-L): From min. to max within range of measurement (FS-H should be over "1" bigger than FS-L)
- Resistive load : Max. 600Ω
- Resolution : 8000 division



6. RS485 communication output

- Address : 0 ~ 99 address(32 channel)
- Retransmission speed(Baud rate) : 2400/4800/9600 bps
- Retransmission code : ASCII
- Parity Bit : No
- Data Bit : 8 Bit
- Stop Bit : 1 Bit
- Communication items
 - MP5W ← PC : Comparative value of each bank data, Prescale value and Peak value, RESET control
 - MP5W → PC : Comparative value of each bank data, Prescale value and Peak value, Display value

Operation mode

- Select operation mode from **mode**(mode) of Parameter 1 group.
- There are 13 kinds of operation mode in this unit.

Mode F1(Frequency/Number of revolution/Speed)

This mode is to display calculated frequency or number of revolution, speed by measuring frequency of Input A.

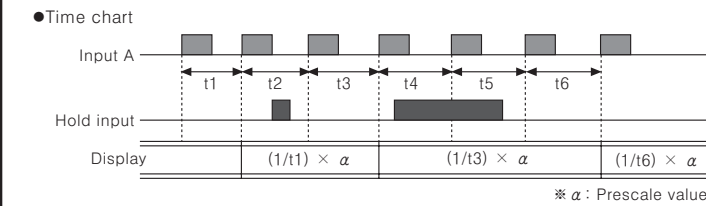
- Frequency(Hz) = $f \times \alpha$ ($\alpha = 1[\text{sec}]$)
- Number of revolution(rpm) = $f \times \alpha$ ($\alpha = 60[\text{sec}]$)
- Speed(m/min) = $f \times \alpha$ ($\alpha = 60L[\text{sec}]$)

*L = The length of conveyor moved for 1 pulse cycle[m]

Display value and display unit

Display value	Display unit	α (Prescale value)
Frequency	Hz	1
	kHz	0.001
Number of revolution	rps	1
	rpm	60
Speed	mm / sec	1,000L
	cm / sec	100L
	m / sec	L
	m / min	60L
	km / hour	3.6L

*Display unit of factory default : rpm



Mode F2(Passing speed)

It displays the passing speed between ON of input A and ON of input B.

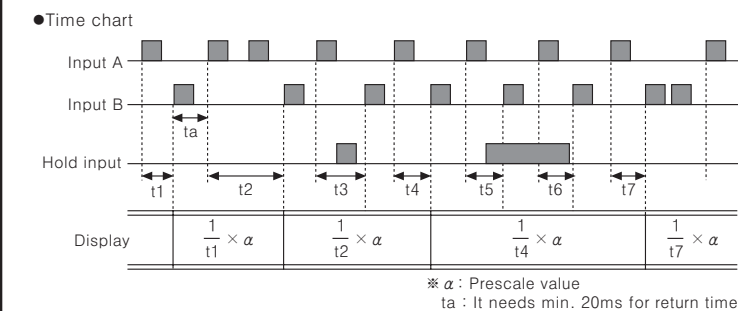
Passing speed(V) = $f \times \alpha$ ($\alpha = L[\text{m}]$)

*f : This is reciprocal number of the time between ON of input A and ON of input B
L : The distance between input A and input B[m]

Display value and display unit

Display value	Display unit	α (Prescale value)
Passing speed	mm / sec	1,000L
	cm / sec	100L
	m / sec	L
	m / min	60L
	km / hour	3.6L

*Display unit of factory default : m/sec



Mode F3(Cycle)

It displays the time from when input A is ON to the next ON of input A.

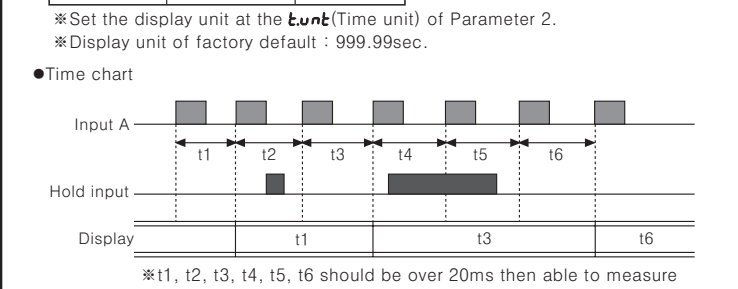
Cycle(T) = t

*t : Measurement time[sec]

Display value and display unit

Display value	Display unit	SEC	MIN
Cycle		999.99sec.	999.99min.
		9999.9sec.	9999.9min.
		99min.	99hour 99min.
		59.9sec.	59.9min.
		9hour 59min. 59sec.	999hour 59min. 59sec.
		99999sec.	99999min.

*Set the display unit at the **Unit**(Time unit) of Parameter 2.
*Display unit of factory default : 999.99sec.



Mode F4(Passing time)

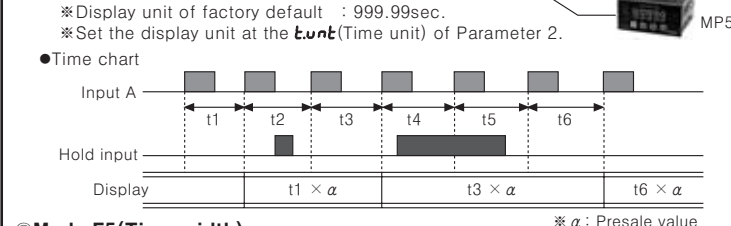
It displays the passing time of certain distance as measuring the time between ON and the next ON of Input A.

Passing time[sec] = $t \times \alpha$ ($\alpha = \frac{L[\text{m}]}{\text{Moving distance within 1 pulse cycle}[\text{m}]}$)

Display value and display unit

Display value	Display unit	
Passing time	SEC	
	MIN	
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99hour 59.9sec.	99hour 59.9min.
	9hour 59min. 59sec.	999hour 59min. 59sec.

*t: Measurement time[sec]
L: Certain distance[m]



Mode F5(Time width)

It displays the ON time of input A.

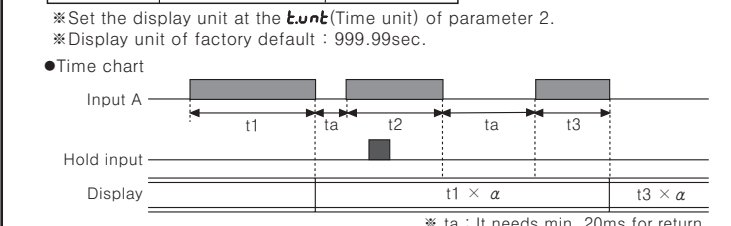
Time width[T] = t

*t : ON measurement time of input A[sec]

Display value and display unit

Display value	Display unit	
Passing time	SEC	
	MIN	
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99hour 59.9sec.	99hour 59.9min.
	9hour 59min. 59sec.	999hour 59min. 59sec.

*Set the display unit at the **Unit**(Time unit) of parameter 2.
*Display unit of factory default : 999.99sec.



Mode F6(Time interval)

It displays the time from input A is ON to input B is ON.

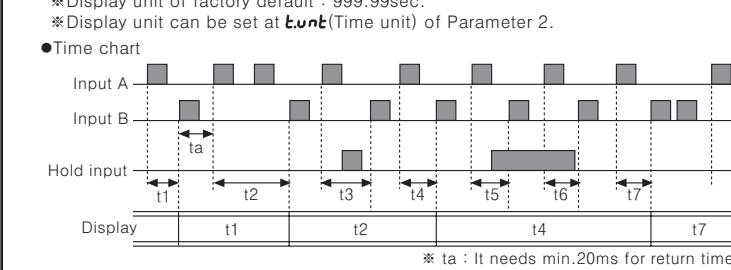
Time difference(T) = t(ta to tb)

*t(ta to tb): The measurement time from input A is ON to input B is ON[sec]

Display value and display unit

Display value	Display unit	
Passing time	SEC	
	MIN	
	999.99sec.	999.99min.
	9999.9sec.	9999.9min.
	99hour 59.9sec.	99hour 59.9min.
	9hour 59min. 59sec.	999hour 59min. 59sec.

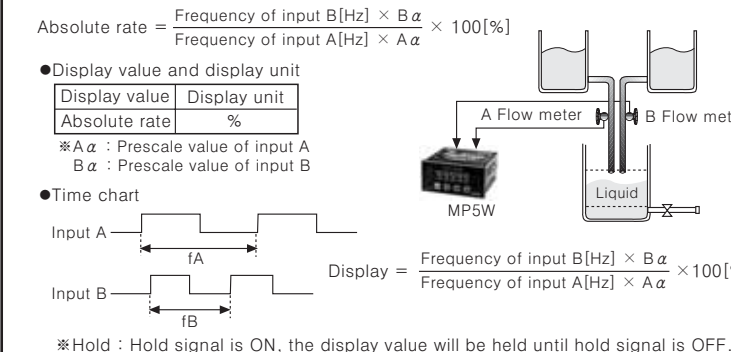
*Display unit of factory default : 999.99sec.
*Display unit can be set at **Unit**(Time unit) of Parameter 2.



Mode F7(Absolute rate)

It displays how many percentage(%) faster or late, speed, volume etc. of Input B against input A

Absolute rate = $(\text{Input B} / \text{Input A}) \times 100\%$

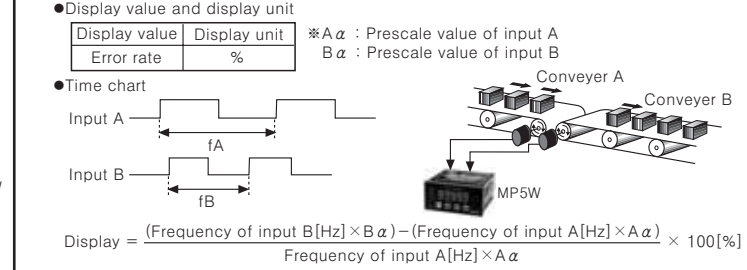


Mode F8(Error ratio)

It displays how many percentage(%) faster or late of Input B against Input A.

Absolute rate = $\frac{\text{Input B} - \text{Input A}}{\text{Input A}} \times 100\%$

Error rate = $\frac{(\text{Frequency of input B}[\text{Hz}] \times B\alpha) - (\text{Frequency of input A}[\text{Hz}] \times A\alpha)}{\text{Frequency of input A}[\text{Hz}] \times A\alpha} \times 100\%$

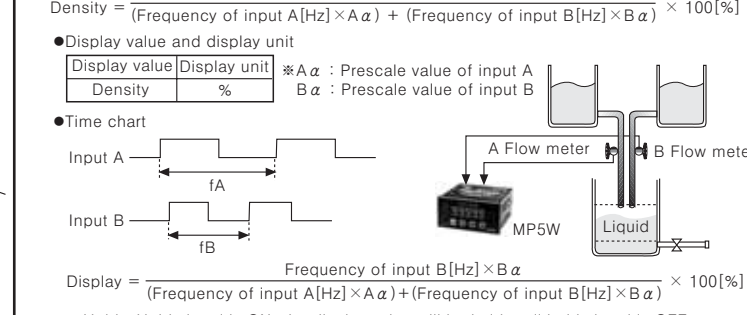


Mode F9(Density)

It displays the density rate of input B against total sum of input A and input B.

Density = $\frac{\text{Input B}}{\text{Input A} + \text{Input B}} \times 100\%$

Density = $\frac{\text{Frequency of input B}[\text{Hz}] \times B\alpha}{(\text{Frequency of input A}[\text{Hz}] \times A\alpha) + (\text{Frequency of input B}[\text{Hz}] \times B\alpha)} \times 100\%$

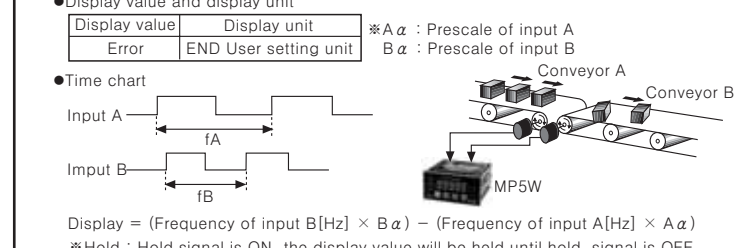


Mode F10(Error)

It displays the error between standard Input A and comparing Input B.

Error = Input B - Input A

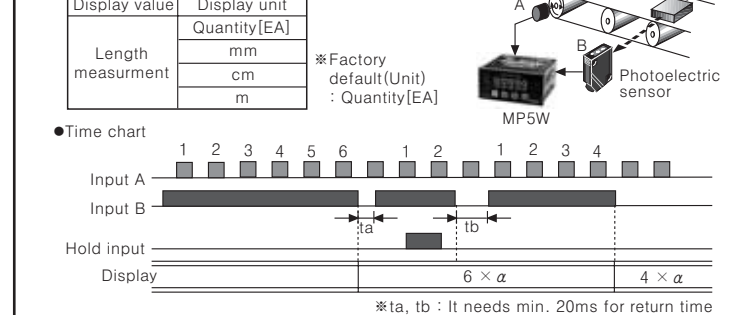
Error = $(\text{Frequency of input B}[\text{Hz}] \times B\alpha) - (\text{Frequency of input A}[\text{Hz}] \times A\alpha)$



Mode F11(Length measurement)

It displays the number of Input A pulse while Input B is ON.

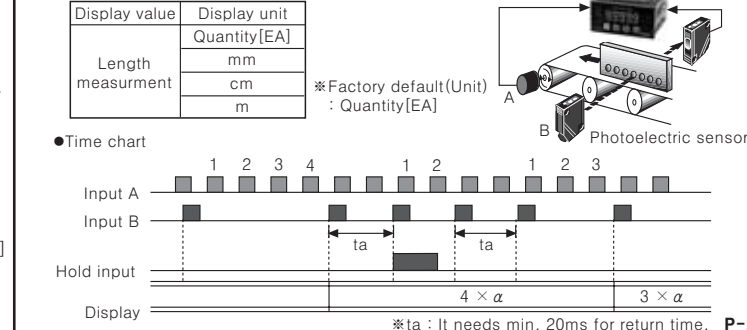
Length measurement = $P \times \alpha$ (*P : Number of input A pulse, alpha : Prescale value)



Mode F12(Interval)

It displays the number of Input A pulse from Input B is ON to the time Input B is ON next.

Interval = $P \times \alpha$ (*P : Number of input A pulse, alpha : Prescale value)



Mode F13(Integration)

It displays the counting value against pulses of Input A.

Integration = P × α

*P : Pulse number of input A, α : Prescale value

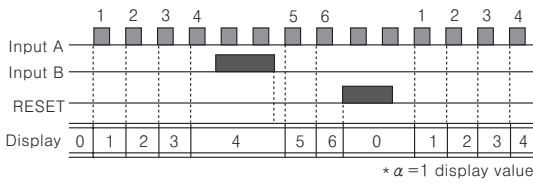
●Display value and display unit

Display value	Display unit
Interval	Quantity[EA]

●Operation and Time chart

①It counts the number of input A pulse.

②As input B is an enable input signal it stops the counting and display value of input A when it is ON and then it counts input A continuously when it is OFF.



Output mode

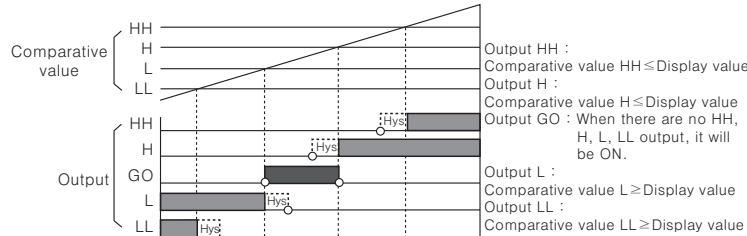
●Select output mode in out-t(output type) of Parameter1 group.

●There are 5 stages output(HH, H, GO, L, LL) and 3 stage output(H, GO, L).

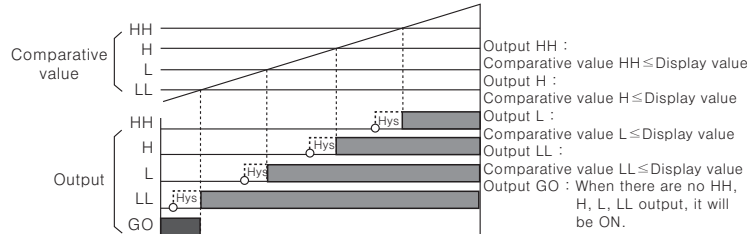
●There are 6 kinds of output mode such as S(Standard) output mode, H(High) output mode, L(Low) output mode, B(Block) output mode, I(One shot)output mode, F(Deviation)output mode.

●The setting value(HH, H, L, LL) should be LL < L < H < HH in B comparative output type and it operates individually not related to the setting value(HH, H, L, LL) in others output(S, H, L, I).

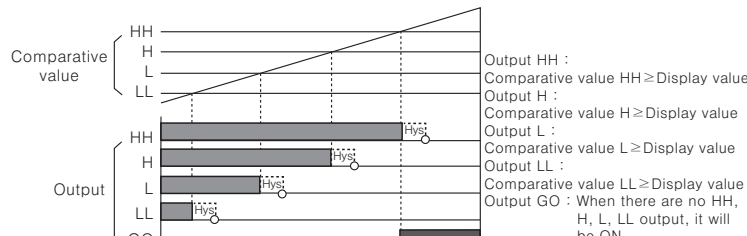
○ S(Standard) output mode[StAr.d]



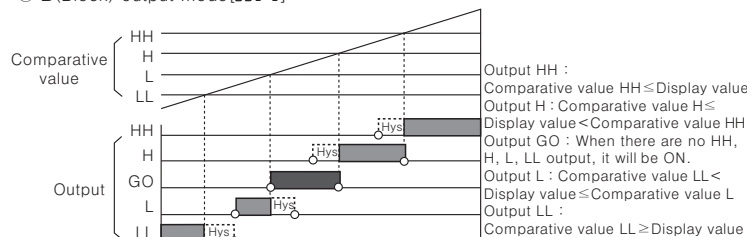
○ H(High) output mode[out-h]



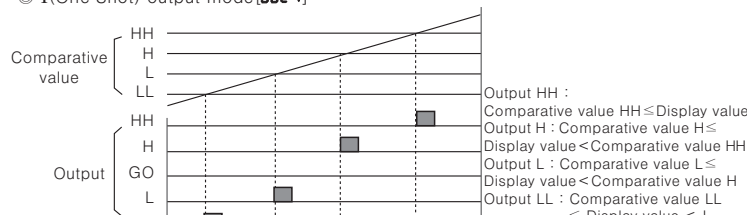
○ L(Low) output mode[out-L]



○ B(Block) output mode[out-b]



○ I(One Shot) output mode[out-I]



*There is no GO output in output I mode.

*One Shot(■) output time has been fixed 0.3sec.

*There is no Hysteresis in I(One shot) comparative output mode.

F(Deflection) output mode[out-F]

This function is to memorize the setting value and provide outputs when it exceeds the deviation of H, L.

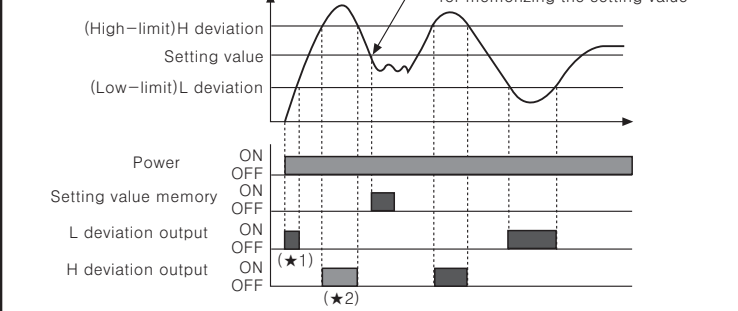
●The setting value memory : Memorize the current display value as the setting value by pressing (M+▲) key in front.

●Display the setting value : Check the memorized setting value by (▲) key. (Display the memorized setting value for pressing ▲ key continuously.)

●Deviation setting : Set H, L deviation by setting value. (The set deviation will be memorized until set the next deviation again when power off.)

●Deviation setting range : 0.0001 to 99999(The setting range will be changed by decimal point setting parameter. If set decimal point as 0000.0, the setting range will be 0.1 to 9999.9.)

●Operation



*(★1)When select the comparative output limit function, output will not be come.
*(★2)Output position may different from above graph as output coming under assuming the setting value memory is before the setting value memory point on above graph.
*There are no HH, GO, LL outputs in F output mode.
*Even though you set the deviation as "0(Zero)", it will actually work as setting "1".

Operation chart by each Parameter group

●The display parameter are different by each operation mode, please see "Parameter".

●○ : When select the operation mode, the parameter will be displayed.
X : When select the operation mode, the parameter will not be displayed.

Parameter 0 group

Parameter 0	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
PSt.hh		○	○	○	○	○	○	○	○	○	○	○	○	○
PSt. h		○	○	○	○	○	○	○	○	○	○	○	○	○
PSt. L		○	○	○	○	○	○	○	○	○	○	○	○	○
PSt.LL		○	○	○	○	○	○	○	○	○	○	○	○	○
h.PEK		○	○	○	○	○	○	○	○	○	○	○	○	X
L.PEK		○	○	○	○	○	○	○	○	○	○	○	○	X

Parameter 1 group

Parameter 1	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
Mode		○	○	○	○	○	○	○	○	○	○	○	○	○
In-A		○	○	○	○	○	○	○	○	○	○	○	○	○
In-b		X	○	X	X	X	○	○	○	○	○	○	○	○
out-t		○	○	○	○	○	○	○	○	○	○	○	○	X
hyS		○	X	X	X	X	○	○	○	○	○	X	X	X
GuAr.d	F.dEFy	○	○	○	○	○	○	○	○	○	○	○	○	X
	StAr.t	○	○	○	○	○	○	○	○	○	○	○	○	X
Auto.A		○	X	X	○	X	X	○	○	○	○	X	X	X
Auto.b		X	X	X	X	X	X	○	○	○	○	X	X	X
mEmo		X	X	X	X	X	X	X	X	X	X	X	X	○

*"○" : IN-b sensor will be set as nPn, h, F or PnP, h, F in mode F11, F12, F13.

Parameter 2 group

Parameter 2	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
P.bAnK		○	○	○	○	○	○	○	○	○	○	○	○	○
dot		○	○	X	X	X	X	○	○	○	○	○	○	○
t.un		X	X	○	○	○	○	X	X	X	X	X	X	X
PSt.hh		○	○	○	○	○	○	○	○	○	○	○	○	○
PSt. h		○	○	○	○	○	○	○	○	○	○	○	○	○
PSt. L		○	○	○	○	○	○	○	○	○	○	○	○	○
PSt.LL		○	○	○	○	○	○	○	○	○	○	○	○	○
PSC.A.x(Note1)		○	○	X	○	X	X	○	○	○	○	○	○	○
PSC.A.y(Note1)		○	○	X	○	X	X	○	○	○	○	○	○	○
PSC.b.H		X	X	X	X	X	X	○	○	○	○	X	X	X
PSC.b.y		X	X	X	X	X	X	○	○	○	○	X	X	X
dISP.t		○	X	X	X	X	X	○	○	○	○	X	X	X

*(Note1)PSC. x, PSC. y are displayed in mode F1, F2, F4, F11, F12, F13.

Parameter 3 group

Parameter 3	Sub mode	F1	F2	F3	F4	F5	F6	F7	F8	F9	F10	F11	F12	F13
FS-h														
FS-L														
Addr														
bPS														
remot														
LoC		○	○	○	○	○	○	○	○	○	○	○	○	○

Monitoring delay function operation chart by each output mode

	out-t	StAr.d	out-h	out-L	out-b	out-I	out-F
Comparative output adjustment function.	○		X	X	○	X	○
Starting correction timer function	○		○	○	○	○	○

Parameter

Parameter 0 group

Menu and Parameter display	Parameter	Setting range	Setting key
	Set HH comparative value	●F1, F2, F7, F9, F11, F12, F13 : 0 to 99999	◀ : Move the setting digit ▼, ▲ : Change the setting value MD : Fix and move to the next parameter
Set H comparative value	Set L comparative value	Set LL comparative value	
Display high peak value among measuring values	Display low peak value among measuring values		●Reset If you press ◀ key for 2sec. while h.PEK or L.PEK is flickering, the Peak value display will be reset to the current measuring value and it will keep flickering. MD If you touch once again, it will return to L.PEK or RUN.

*(★1)If you press MD key in RUN mode, it will enter into PSt.hh(F output mode:PSt. h) at comparative output mode and h.PEK at indication type.

*When entering into parameter 0, the parameter and data will be flickering by 1 sec. then moving the setting digit and changing the setting value are available.

*It will show the set data to flicker by 1sec., then move to next Parameter with touching MD key once.

Parameter 1 group

Menu and Parameter display	Parameter	Setting range	Setting key
	This is parameter 1 group.		
Select operation mode.	F1 to F13	▼, ▲ : Change the setting mode MD : Fix and move to the next parameter	
Set the sensor type of input A.	• PNP transistor output type : PnP.h.F • Contact output type(L output) : PnP.L.F • NPN transistor output type : nPn.h.F • Contact output type(H output) : nPn.L.F	▼, ▲ : Change the sensor type MD : Fix and move to the next parameter	
Set the sensor type of input B.			
Select the output mode. (★1)	StAr.d / out-h / out-L out-b / out-I / out-F	▼, ▲ : Change the setting mode StAr.d → out-h → out-L out-F ← out-I ← out-b MD : Fix and move to the next parameter	
Set the hysteresis for the output. (★2)	0 to 9999 (If decimal point is set in 0000.0, the range will be 0 to 9999.)	◀ : Move the setting digit ▼, ▲ : Change the setting value MD : Fix and move to the next parameter	
Select the start compensating timer function or comparative output(L, LL) limit function. (★3)	① F.dEFY / StAr.t ② When select StAr.t When [StAr.t] is flickering by 1sec. cycle, set the starting correction time 0.0 to 999.	① ▼, ▲ : Change the setting mode MD : Fix and move to the next parameter ② ◀ : Move the setting digit ▼, ▲ : Change the setting value MD : Fix and move to the next parameter	
Set the Auto-zero time of INA input.	0.1 to 9999.9	◀ : Move the setting digit ▼, ▲ : Change the setting value MD : Fix and move to the next parameter	
Set the Auto-zero of INB input.	0.1 to 9999.9	◀ : Move the setting digit ▼, ▲ : Change the setting value MD : Fix and move to the next parameter	
It sets the memory retention. The measuring value will be memorized when the power off. (Mode F13 only)	on : Memory retention off : No memory retention	▼, ▲ : Change the setting mode MD : Fix and move to the next parameter nodE	

*If press MD key for 3 sec. in RUN, it will enter into parameter 1 group.

*(★1)It will not be displayed in indication type.

The output mode is fixed as out-h type in F13 operation mode.

*(★2)Hysteresis operation mode is able to be set in F1, F7 to F10 operation mode.

*(★3)You are able to select the comparative output limit function or starting correction [StAr.t] timer in monitoring delay function mode.

When selecting the comparative output limit function, it will move to the next parameter [Auto.A] and when selecting the starting correction timer [StAr.t] you need to be set the starting correction time [0.0 - 999] so that it moves to the next parameter [Auto.A].

*If press MD key for over 2 sec. in every setting mode, data will be set and return to RUN.

*When entering into parameter 1 group, the parameter name and data will be flickering by 1 sec. then move setting digit by ◀ key or change the setting value by ▼, ▲ key.

*All data set by users will be shown[displayed] to 1sec. cycle then move to the next parameter by pressing MD key.

