# Panasonic ideas for life



**Motion Control** 

AC Inverters VF-0, VF-CE



# AV Inverters VF-0, VF-CE

# **Product Overview**

### **VF-0 Series**

- Ultra-compact
- Easy to use
- Cost effective

### 1-phase 230V AC

0.2 kW 0.4 kW 0.75 kW 1.5 kW



### 3-phase 400V AC

0.75 kW 1.5 kW 2.2 kW 3.7 kW



### **VF-CE Series**

- Vector control
- Advanced technology
- Filter integrated
- Multiple interfaces (RS232C/RS485, PROFIBUS)

### 1-phase 230V AC

0.25kW

0.37kW

0.75 kW

1.5 kW

2.2kW

### 3-phase 400V AC

0.75 kW

1.5 kW

2.2 kW

4.0kW











# **VF-0 Series**

## Overview

### **Highlights**

- Ultra-compact
- Easy to operate using the integrated operating panel
- Cost effective
- Easy and accurate frequency control using PLC puls output
- Various types without and with brake included (1-phase)
- 8-speed control function
- Retry function
- Frequency increase, decrease and memory functions using external switches
- Complete regeneration brake function

### 1-phase 230V AC Input types

	Part N	lo.
MotorPower P <sub>N</sub>	Brak	
[kW]	provided	not provided
0.2		BFV00022DK
0.4	BFV00042GK	BFV00042DK
0.75	BFV00072GK	BFV00072DK
1.5	BFV00152GK	BFV00152DK

3-phase 400V AC Input types	
MotorPower P <sub>N</sub>	Part No.
[kW]	
0.75	BFV00074
1.5	BFV00154
2.2	BFV00224
3.7	BFV00374

### Easy to operate

Button to select "frequency output, current display", "frequency setting, monitor", "rotation direction setting", "function setting" and switching the display to show data or mode

Button to change the display between the parameter No. and data display, and save the data, also to change between frequency and current display

Potentiometer to set the operating frequency



Display shows output frequency, current, line speed, error details, data for function setting and parameter numbers

Button to start the inverter

Button to stop the inverter

Up/Down buttons to change the data and output frequency, and to set forward or reverse run direction

### Easy and accurate frequency control with a PLC





# VF-0 Series

# Specifications

Applied motor output    Secretary   Spains   Spa		Input v	oltage	1-phase 230V AC	3-phase 400V AC		
Based couptor Wanges   3-phase 310 to 280' AC [unportenant to power supply valuage]   3-phase 380 to 460' AC 500'01tz   50% of rated output current for 1 minute   3-phase 380 to 460' AC 500'01tz   3-phase 380				-			
Phases voltage, frequency    Phase 200 to 230V AC 504081z   Solid Section   Phase 200 to 230V AC 504081z   Phase 200 to 240V	토모		· · · · · · · · · · · · · · · · · · ·				
Phases voltage, frequency    Phase 200 to 230V AC 504081z   Solid Section   Phase 200 to 230V AC 504081z   Phase 200 to 240V	Rate	Overload					
Tolerable voltage variations   10%, -15% of rated AC Input voltage   25% of rated upt frequency   25% of rated functions   25% of rated function		Dhacos vo		-			
Continuous operation at less than 165V for 15ms   Continuous operation at less than 323V for 15	pply	Tolerable v		•			
Continuous operation at less than 165V for 15ms   Continuous operation at less than 323V for 15	nput r su	Torerable frequency variations					
Continuous operation at less than 165V for 15ms   Continuous operation at less than 323V for 15	ll owe	Instanta					
Prequency display   Digital display   Frequency display   Prequency (25±10°C) for analogue setting   DiB/ (18/00°C)   Prequency setting resolution   Digital setting   DiB/ (18/00°C)   Diamondary   Digital setting   DiB/ (18/00°C)   Diamondary   DiB/ (18/00°C)   Diamondary   Dib/ (18/00°C)   Diamondary	d	drop resis			Continuous operation at less than 323V for 15ms		
Frequency display   Digital display   Frequency display   Prequency (25±10°C) for analogue setting   Prequency   Prequency setting southern   Prequency (25±10°C) for analogue setting   Prequency   Prequency setting   Prequency   Prepuency   Prep		Output frequency range		0.5 to	250Hz		
Inverter control method    Inverter control method	ut	Freque					
Inverter control method    Inverter control method	ont)	Freque			1 7		
Inverter control method   High carrier frequency sinusoidal PVM control (VF control method)	fi	Frequency					
Select from 1 types (the output current must be reduced for 12 5 and 15 0kHz) (0.8, 1.1, 1.6, 2.5, 5.0, 7.5, 10, 12.5, 15 kHz)  Start/Stop  Forward/Reverse  Operation panel buttons or input contact* signal (wait time setting possible)  Forward/Reverse  Operation panel buttons or input contact* signal (wait time setting possible)  Jog operation  Operating frequency-Optional setting for 15 to 25 2016. A celevation-deceleration time: Optional setting possible)  Reset function  Stop signal reset, external reset, panel reset (setting possible) and power supply reset  Optional setting from 0.5 to 60 file  Rest function  Retry selection: Select function OFF and details of retry fault. No. of retries: Optional setting for 1 to 10 time  * * * * * * * * * * * * * * * * * * *							
(0.8, 1.1, 1.6, 2.5, 5.0, 7.5, 10, 12.5, 154Rz)   The output current of 37MW must be reduced when set to 10ME							
Start/Stop   Operation panel buttons or input contact" signal (wait time setting possible)		Carrier fr	equency	(The output current must be reduced for 12.5 and 15.0kHz)	(0.8, 1.1, 1.6, 2.5, 5.0. 7.5, and 10kHz)		
Forward/Reverse Operation panel buttons or input contact" signal (reverse rotation prohibit setting possible)  Jog operation Operating frequency: Optional setting for 50 to 2008. Acceleration deceleration time: Optional setting goal of 10 to 10 to 199 sect Stop mode  Reset function Stop signal reset, external reset, panel reset (setting possible) and power supply reset Optional setting from 0.5 to 60012.  Reset function Retry selection: Select function OFF, and offiz restart, operating frequency restart (selection changeover)  Retry function Retry selection: Select function OFF and details of retry fault, No. of retries: Optional setting for 1 to 10 time. Prequency setting signal  Frequency setting signal  Frequency setting signal  Frequency setting signal  Frequency setting signal  Voltage/frequency characteristics  Pad voltage/frequency characteristics  And voltage/frequency characteristics  Frequency setting signal  Voltage/frequency characteristics  And voltage/frequency characteristics  Frequency setting for 0.5 to 50012.  And voltage/frequency characteristics  Frequency setting for 0.5 to 20012.  F							
Stop mode   Select from ramp-to-stop or coast-to-stop (selection changeover)			•	1 1 1	01		
Solution   Select from ramp-to-stop or coast-to-stop (selection changeover)							
Stop frequency   Optional setting from 0.5 to 60Hz	uo –		-				
Stop frequency   Optional setting from 0.5 to 60Hz	erati						
Instantaneous power failure restart   Retry function   Retry selection. Select function OFF, and Ollz restart, operating frequency restart (selection changeover)	ğ-  —						
Retry function  Retry selection: Select function OFF and details of retry fault, No. of retries: Optional setting for 1 to 10 time  *Local setting; Potentiometer, digital setting (operation pane)  *External analog setting signal*  Potentifioneter (10kW, 1/42 or more), 0 to 5V, 0 to 10V, 4 to 20mA (Connect a 20062, 1/4W or more external resistor)  *External analog setting signal PPM signal (signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal  Base frequency: 50, 60Hz fixed and optional setting between 45 and 250Hz V/F curve: Constant torque, square torque pattern (selection changeover)  2nd voltage/frequency characteristics  Optional base frequency setting for 0 to 40%  1st and 2nd accel/Decel. Time  Multi-speed frequency setting  Up to 3 place settings (skip frequency settings (optional setting) for 0 to 40%  Skip frequency setting  Up to 3 place settings (skip frequency settings (optional setting) from 0.5 to 250Hz  Bias/gain frequency setting  Dyper and lower frequency settings  Bias frequency: set from -99 to 250Hz, Gain frequency: set from 0 to 250Hz  External stop function  Select from auxiliary stop or coast-to-stop (selection setting)  External stop function  O4kW: 100% or more (shrt-time)  O2kW: 100% or more (shrt-time)  O2kW: 100% or more (shrt-time)  O2kW: 100% or more, 0.4kW: 80% or more  O75kW: 20% or more  O4kW: 80% or more  O5kW: 20% or more  O4kW: 80% or more  O4kW: 80% or more  O5kw: 20% or more  O4kW: 80% or more  O5kW: 20% or more  O4kW: 80% or more  O5	H		1 3	1 0			
**Local setting: Potentiometer, digital setting (operation panel)   **External analog setting signal: Potentiometer (10kW, 1/4g or more), 0 to 5V, 0 to 10V, 4 to 20mA (Connect a 2002, 1/4W or more external resistor)   **External digital setting signal: Potentiometer (10kW, 1/4g or more), 0 to 5V, 0 to 10V, 4 to 20mA (Connect a 2002, 1/4W or more external resistor)   *External digital setting signal: PWM signal (signal cycle: 0.9 to 1100ms). Frequency up SW, down SW, save SW signal Base frequency contacteristics   Surface of the cycle of the cy	-						
Frequency setting signal  Frequency setting signal:  Potentiometer (10kW, 1/4Q or more) to 5V, 0 to 10V, 4 to 20mA (Connect a 2002, 1/4W or more external resistor)  External digital setting signal: PWM signal (signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency up SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency DSW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency DSW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency DSW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 1100ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency SW, down SW, save SW signal (Signal cycle: 0.9 to 400ms), Frequency Sw signal (Signal cycle: 0.9 to 400ms)		Retry	function				
External digital setting signal: PWM signal (Sonnact a 2002, 1/4W or more external resistor)		Frequency setting signal					
Voltage/frequency characteristics  Passe frequency: 50, 60Hz fixed and optional setting between 45 and 250Hz V/F curve: Constant torque, square forque pattern (selection changeover)  Potional base frequency setting for 0 to 40%  Ist and 2nd otcape-frequency setting  Ist and 2nd accel-/Decel. Time  Multi-speed frequency setting  Skip frequency setting  Skip frequency setting  With orange of potional setting for 0 to 40%  Ist and 2nd lower frequency setting  With orange of potional setting for 0 to 40%  Ist and 2nd lower frequency setting  With brakes  Regenerative braking torque  With brakes  O-4kW, 0.75kW, 1.5kW: 100% or more (short-time)  O'25kW: 100% or more, 0.4kW: 80% or more 0.75kW: 20% or more, 1.5kW: 20% or more 0.75kW: 20% or more, 1.5kW: 20% or more 0.75kW: 30% or mo				4 to 20mA (Connect a 200Ω, 1/4W or more external resistor)			
The voltage/frequency characteristics    Optional base frequency setting for 45 to 250Hz							
Ist and 2nd torque boost level   Optional base frequency setting for 45 to 250Hz		Voltage/frequency characteristics					
Ist and 2nd torque boost level   Optional setting for 0 to 40%	l	2nd voltage/frequency characteristics					
Skip frequency setting	itrol –	1st and 2nd targue boost level					
Multi-speed frequency setting   Up to 8 preset frequency settings (optional setting)	Co.						
Skip frequency setting   Up to 3 place settings (skip frequency band setting from 1 to 10Hz)							
Upper and lower frequency setting  Bias/gain frequency settings  Bias frequency: set from -99 to 250Hz, Gain frequency: set from 0 to 250Hz  External stop function  Select from auxiliary stop or coast-to-stop (selection setting)  With brakes  O.4kW, 0.75kW, 1.5kW: 100% or more (short-time)  DC braking  Operates when less than stop frequency. Braking time: Optional setting for 0.1 to 120 seconds  Analogue output  Output specifications: 0 to 5V (max. ImA), Output functions: Output frequency, output current proportional (selection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle 1ms)  Output specifications: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current overload (OL), low voltage (UU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation or coast-to-stop (selection setting)  Dovercurrent stall prevention, regenerative overvoltage stall prevention	H						
Bias/gain frequency settings  External stop function  Select from auxiliary stop or coast-to-stop (selection setting)  Regenerative braking torque  With brakes  O.4kW, 0.75kW, 1.5kW: 100% or more (short-time)  O.2kW: 100% or more, 0.4kW: 80% or more 0.75kW: 20% or more 100% or more with connection of brake resistor (opt (built-in brake circuit)  DC braking  Operates when less than stop frequency, Braking torque level: 0 to 100 (set between 20 levels), Braking time: Optional setting for 0.1 to 120 seconds  Analogue output  Output specifications: 0 to 5V (max. ImA), Output frequency, output current proportional (selection changed Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle 1ms)  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (UU), overvoltage (UU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention							
External stop function   Select from auxiliary stop or coast-to-stop (selection setting)							
Regenerative braking torque  With brakes  O.4kW, 0.75kW, 1.5kW: 100% or more (short-time)  O.2kW: 100% or more, 0.4kW: 80% or more 100% or more with connection of brake resistor (opt (built-in brake circuit)  DC braking  Operates when less than stop frequency, Braking torque level: 0 to 100 (set between 20 levels), Braking time: Optional setting for 0.1 to 120 seconds  Output specifications: 0 to 5V (max. Ima), Output functions: Output frequency, output current proportional (selection changed Output specifications: Max. rating 50V DC, 50mA  Output specifications: Max. rating 50V DC, 50mA  Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle Ims)  Operating condition  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (UL), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention							
Regenerative braking torque  Without brakes  0.2kW: 100% or more, 0.4kW: 80% or more 0.75kW: 20% or more 1.00% or more with connection of brake resistor (opt (built-in brake circuit)  DC braking  Operates when less than stop frequency, Braking torque level: 0 to 100 (set between 20 levels), Braking time: Optional setting for 0.1 to 120 seconds  Analogue output  Output specifications: 0 to 5V (max. Inal), Output functions: Output frequency, output current proportional (selection changed Output specifications: Max. rating 50V DC, 50mA Output specifications: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle Ims)  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Shut-off (stop)  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (UU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention		Zitterinar i	•	ÿ 1			
DC braking  DC braking  Operates when less than stop frequency, Braking torque level: 0 to 100 (set between 20 levels), Braking time: Optional setting for 0.1 to 120 seconds  Output specifications: 0 to 5V (max. InA), Output functions: Output frequency, output current proportional (selection changed Output specifications: Max. rating 50V DC, 50mA Output specifications: Max. rating 50V DC, 50mA Output functions: Run signal, arrival signal, overload prealarm, freuquency detection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle Ims)  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention	20				20% or more 100% or more with connection of brake resistor (option)		
DC braking  Operates When less than stop frequency, braking torque level: 0 to 100 (set between 20 levels), Braking time: Optional setting for 0.1 to 120 seconds  Analogue output  Output specifications: 0 to 5V (max. ImA), Output functions: Output frequency, output current proportional (selection changed Output specifications: Max. rating 50V DC, 50mA Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle 1ms)  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit and be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (UU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention	akin	braking torque	Without brakes				
Analogue output  Open collector output  Output specifications: 0 to 5V (max. 1mA), Output functions: Output frequency, output current proportional (selection changed Output specifications: Max. rating 50V DC, 50mA Output functions: Max. rating 50V DC, 50mA Output functions: Run signal, arrival signal, overload prealarm, freuquency detection, reverse run signal, fault warning, output functions: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention	Br	p. 0.1	11 .	Operates when less than stop frequency. Braki	ng torque level: 0 to 100 (set between 20 levels),		
Output specifications: Max. rating 50V DC, 50mA Output functions: Run signal, arrival signal, overload prealarm, freuquency detection, reverse run signal, fault warning, output frequency/current proportional PWM signal (cycle 1ms)  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition Output firequency or line speed (selection changeover), output current, rotation direction  Fault details Symbol indicated when protective function activates (last 4 faults are stored)  Current limit Current limit and be set from 1 to 200% of rated output current  Shut-off (stop) Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function Overcurrent stall prevention, regenerative overvoltage stall prevention		DCI	лакіпд				
Relay output  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention		Analog	ue output		out frequency, output current proportional (selection changeover)		
Relay output  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention	gna	0 "	a atan autot		darm frauquancy dataction mayones man = -11		
Relay output  Output specifications: change over (1c) contact (contact capacity 250V AC, 0.5A resistance load) Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output frequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention	ut si	Upen coll	ector output				
Output functions: Run signal, arrival signal, overload prealarm, frequency detection, reverse run signal, fault warning  Operating condition  Output firequency or line speed (selection changeover), output current, rotation direction  Fault details  Symbol indicated when protective function activates (last 4 faults are stored)  Current limit  Current limit can be set from 1 to 200% of rated output current  Instantaneous overcurrent, over temperature (SC1 to 3), overcurrent (OC 1 to 3), overload/electronic thermal overload (OL), low voltage (IU), overvoltage (OU 1 to 3), auxiliary stop (AU), operation error (OP)  Stall prevention function  Overcurrent stall prevention, regenerative overvoltage stall prevention	Outp						
Current limit   Current limi		Relay	youtput				
Current limit   Current limi	lay	Operating condition		Output frequency or line speed (selection ch	nangeover), output current, rotation direction		
Current limit   Current limi	Disp	1 0					
Stall prevention Overcurrent stall prevention, regenerative overvoltage stall prevention							
Stall prevention Overcurrent stall prevention, regenerative overvoltage stall prevention	ction			•			
Stall prevention Overcurrent stall prevention, regenerative overvoltage stall prevention	rote	Shut-off (stop)					
	Н	Stall preve	ntion function	Overcurrent stall prevention, regen	erative overvoltage stall prevention		
Working ambient temperature and humidity -10°C to +50°C (with no freezing), 90% RH or less (with no dew condensation)	ant	Working ambient ter	mperature and humidity	-10°C to +50°C (with no freezing), 90%	RH or less (with no dew condensation)		
Transportation/storage temperature and humidity  -25°C to +65°C, 95% RH or less	nme	Transportation/storage	temperature and humidity	-25°C to +65°C,	95% RH or less		
Working ambient temperature and humidity  -10°C to +50°C (with no freezing), 90% RH or less (with no dew condensation)  Transportation/storage temperature and humidity  -25°C to +65°C, 95% RH or less  Altitude and vibration  1000m or 1685, 5.9m/s² (0.6G) or less	nviro	Altitude a	nd vibration	1000m or less, 5.9	m/s <sup>2</sup> (0.6G) or less		
Atmosphere Indoors, with no corrosive gases, explosive gases, oil mist or dust present	E I	Atmo	osphere	Indoors, with no corrosive gases, ex	plosive gases, oil mist or dust present		
Enclosure IP00		Enclo	sure	IP	00		
Cooling method Self-cooling: 0.2 to 0.75kW, Forced-air cooling: 1.5kW Self-cooling: 0.75kW, Forced-air cooling: 1.5 to		Cooling	method	Self-cooling: 0.2 to 0.75kW, Forced-air cooling: 1.5kW	Self-cooling: 0.75kW, Forced-air cooling: 1.5 to 3.7kW		

Protection against Electric shock: Class I • Overvoltage category: II • Pollution degree: 2
 Note: The specifications for the 200V and 400V classes are not the same. Please keep in mind this partial difference.

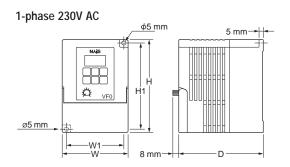
 $<sup>\</sup>overline{}^{1)}$ 1a = Normally open

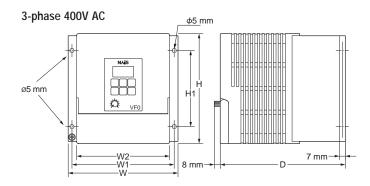


# **VF-0 Series**

# Specifications

### **Dimensions**





Part No.	Applicable Motor Capacity [kW]	W [mm]	W1 [mm]	H [mm]	H1 [mm]	D [mm]
BFV00022DK	0.2					
BFV00042DK	0.4	78	68	110	102	100
BFV00042GK	0.4					
BFV00072DK	0.75					
BFV00072GK	0.75	100	90	130	121	115
BFV00152DK	1.5	100	70	130	121	113
BFV00152GK	1.5					

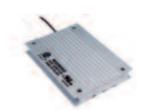
Note 1: 1.5kW includes a cooling fan

Part No.	Inverters Capacity [kW]	W [mm]	W1 [mm]	W2 [mm]	H [mm]	H1 [mm]	D [mm]
BFV00074	0.75	130	121	110	130	90	148
BFV00154	1.5	120	101	110	120	00	1/1
BFV00224	2.2	130	121	110	130	90	161
BFV000334	3.7	160	151	140	130	90	161

Note 1: 1.5 to 3.7kW includes a cooling fan

### **Brake resistor**

VF-0 Part No.	Motor [kW]	Brake resistor Part No.	Dimensions [mm]
BFV00074	0.75kW 3-phase 400V	BFVC9164U	110 x 80 x 15
BFV00154	1.5kW 3-phase 400V	BFVC9164U	110 x 80 x 15
BFV00224	2.2kW 3-phase 400V	BFVC9165U	110 x 80 x 15
BFV00374	3.7kW 3-phase 400V	BFVC9166U	216 x 80 x 15



For 1-phase 230 V AC types please select the BFV00042GK, BFV00072GK or BFV00152GK.

The brake resistor is either enclosed, or built in.

### **Filters**

EMC filters are usually employed to reduce conducted disturbances and thus ensure constant quality in the power supply network.

For use, the standards EN61800-3 (product standard) and EN55011/EN55022 (limits and methods of measurement) are important, whereby the following limits must be met: EN55011/EN55022, Class A: Limits for general industrial use. This applies to all usage sites that are normally connected to their own individual high- of medium-high voltage transformer.

Inverter	$P_{N}$	EMC Filter	Compliant to	Part No.
VF-0 1-phase	0.2kW – 1.5kW	200V type	EN55022 Class A and B	FN2071N606
VF-0 3-phase	0.75kW – 3.7kW	400V type	EN55022 Class A and B	FN3258745



# Overview

### For the 0.25kW to 4.0kW power range

- Ultra-compact
- · Integrated filter with EMC interference to class B
- Vector control and V/f control
- Up to 1.8 x  $M_N$  torque for 60s ( $M_N$  = rated load torque)
- Multiple interfaces (digital/analogue I/O, RS232/RS485, PR0FIBUS)
- · Operator module with copy function
- · International approvals (CE, UL, cUL)
- · Cost effective

- · Energy efficient
- Types: 1-phase 230V AC: 0.25 to 2.2kW
   (1-phase 115V AC power supply also possible with restrictions)
   3-phase 400V AC: 0.75 to 4.0kW
   (3-phase 200V AC power supply also possible with restrictions)

### Available Communication I/O modules

### For Automation interface AIF



BFVC904C Keypad



BFVC9503 RS232C/RS485 Communication module



BFVC9901 PROFIBUS AIF DP slave interface

### System units

### For Function interface FIF



BFVC90XY Standard I/O Modul (always included) with digital and analogue I/O



BFVC9902 PROFIBUS DP slave interface FIF









For detailed description of the modules see page 8/9.



# **Specifications**

### Improved vector control increases efficiency

Due to vector control, the VF-CE inverter achieves considerably higher torque in comparison to conventional V/f control (maximum torque = 1.8 x MN for 60s) and has low level open-circuit power consumption. This function is particularly useful for drives with strong fluctuating loads or high starting inertia, as well as for sensorless speed control of motors requiring slip compensation.

### Integrated EMC filter to class B – new for VF-CE inverters

VF-CE inverters offer a new concept for preventing electrical interference. For the first time ever, the EMC filters are not connected externally in series. Since many small EMC components are located at the points on the printed circuit board where interference is actually generated, it can be prevented right at the source. The result is a higher filter performance, lower costs and a VF-CE inverters even more compact than before.

Performance	Part No.	Supply Voltage	Supply Voltage	Power P <sub>N</sub> for USA	Dimensions
		(45 – 65Hz)	(1 ~ 115V AC/3 ~ 200\	/ AC)	(H x W x D) in mm
1-phase 230V AC:					
0.25kW	BFVCE0022A	1 ~ 180 – 264V AC	1 ~ 115V AC: 0.12kW	0.16HP	120 x 60 x 140
0.37kW	BFVCE0032A	1 ~ 180 – 264V AC	1 ~ 115V AC: 0.18kW	0.24HP	120 x 60 x 140
0.75kW	BFVCE0072A	1 ~ 180 – 264V AC	3 ~ 200V AC: 0.75kW	1HP	180 x 60 x 140
1.5kW	BFVCE0152A	1 ~ 180 – 264V AC	3 ~ 200V AC: 1.5kW	2HP	240 x 60 x 140
2.2kW	BFVCE0222A	1 ~ 180 – 264V AC	3 ~ 200V AC: 2.2kW	3HP	240 x 60 x 140
3-phase 400V AC:					
0.75kW	BFVCE0074A	3 ~ 320 – 550V AC		1HP	180 x 60 x 140
1.5kW	BFVCE0154A	3 ~ 320 – 550V AC		2HP	240 x 60 x 140
2.2kW	BFVCE0224A	3 ~ 320 – 550V AC		3HP	240 x 60 x 140
4.0kW	BFVCE0404A	3 ~ 320 – 550V AC		5.4HP	240 x 100 x 140

Other types available on demand

Accessories / Interfaces		
Туре	Description	Part No.
Operator module	for entering the parameters; with copy function	BFVC 904C
Remote control set with operator module	for flexible manual operation with cable connection	BFVC 9060
2m cable for remote control set		BFVC 9062
5m cable for remote control set		BFVC 9065
Standard I/O module	digital and analogue inputs/outputs (always included)	BFVC 90XY
RS232C/RS485	RS232C and RS485 (multi-drop) for connection to	DEMO DEDO
communication module	computer or PLC	BFVC 9503
Cable RS232C to PC-AT	Connection cable between VF-CE RS232C port and	BFVC 9503 PCAT
Cable R3232C to PC-AT	computer RS232C port	DF VC 9303 PCAT
Coble DC222C to DLC	Connection cable between VF-CE RS232C port and	DEVC 0E02 DLC
Cable RS232C to PLC	PLC RS232C port, SUB-D 9pin	BFVC 9503 PLC
PROFIBUS AIF module	PROFIBUS interface for connection on AIF	BFVC 9901
PROFIBUS FIF module	PROFIBUS interface for connection on FIF	BFVC 9902
	for 1-phase 0.75kW – 1.5kW inverter *)	BFVC 9161U
	for 1-phase 2.2kW inverter	BFVC 9162U
Braking resistors	for 3-phase 0.75kW – 1.5kW inverter	BFVC 9164U
	for 3-phase 2.2kW inverter	BFVC 9165U
	for 3-phase 4.0kW inverter	BFVC 9166U
Swiveling mounting bracket	for side mounting of 1.5 and 2.2kW inverter	BFVC 9999
Motion Control Software Ver. 2.0	Inverter configurator software for the inverters and VF-CE	BFVS 29902V2

<sup>\*) 0.25 / 0.37</sup> kW brake resistor on request



# The VF-CE inverter's interfaces

### 1. The standard I/O module

It provides parallel, direct connection of peripherals such as PLC, sensors, etc. and offers a variety of connection possibilities.

	Number	Voltage	Current	Resolution
Analogue input	1	0 10V -10 +10V	0/4 20mA	10bits 10bits
Analogue output	1	0 10V	2mA	10bits
Digital inputs	3/4	PLC level		
Frequency input	1/0 (0 10kHz)	0/15V (HTL)		
Digital output	1	0/24V	10/50mA	

One relay output (changeover contact) is integrated into the system unit as standard. (AC 240V/3A, DC 24V/2A ... 200V/0.18A)

The standard I/O module order number BFVC 90XY is included in the VF-CE inverter. It needs not be ordered separately.

### 2. The RS232C / RS485 communication module

Two serial interfaces allow the VF-CE inverter to communicate with the application device and have its parameters adjusted by a controller simultaniously.

### RS232C interface:

- Information message format: 7 bits ASCII, 1 stop bit, 1 start bit, 1 parity bit (even)
- Bit rate: 1.2 / 2.4 / 4.8 / 9.6 / 19.2 kBaud
- Access to all parameters
- DC supply: internal (5V)
- Electric isolation from control/power section

### RS485 interface:

- Information message format: 7 bits ASCII, 1 stop bit, 1 start bit, 1 parity bit (even)
- Bit rate: 1.2 / 2.4 / 4.8 / 9.6 / 19.2 kBaud
- Max. distance between 2 stations: 1200m
- Number of stations: max. 90 (with repeater)
- DC supply: internal

### 3. The PROFIBUS modules

Two different PROFIBUS modules permit open communication in accordance with the international EN50170 standard. The PROFIBUS FIF module is used instead of the standard I/O module. If the standard I/O module is necessary in the application, the PROFIBUS AIF module can be used as the automation interface.

- Bit rate: 9.6 kBaud ... 12 MBaud (automatic detection)
- Max. cable length: 1.2km (depends on baud rate and cable)
- Number of stations: 32 (with repeater 125)
- PROFIBUS status: Slave
- Communication profile: PROFIBUS-DP (DIN 19245, parts 1 and 3)
- Drive profile: DRIVECOM Profile 20
- Access to all parameters

Standard I/O module BEVC90XY



RS232C/RS485 communication interface



Profibus Interface AIF BFVC9901



Profibus Interface FIF





# Operator module

### The VF-CE inverter operator module keypad

The operator module allows you to enter or change the VF-CE parameters as well as display the current drive parameters. The VF-CE parameters can be saved in the operator module (BFVC904C) and simply copied to another VF-CE inverter. Time-consuming parameter setting for larger applications is therefore no longer required and errors are reduced accordingly. The VF-CE inverter operator module can be directly plugged into the VF-CE AIF interface or operated as a remote control set with a 2m or 5m cable. The remote-control set can also be installed in control cabinets and operator consoles.

The operator module is not included in the VF-CE inverter. It is available as an option.

### Key functions of the operating module:



Enable inverter

Inhibit inverter or quick-stop



Change to function bar  $1 \longleftrightarrow$  function bar 2



To right/left in an active function bar



Increase/decrease value



Store Parameter/Acknowledgement



Operator module keypad BFVC904C

### The remote control set with operator module

The operator module (BFVC904C) is already integrated. The 2m or 5m cables are supplied separately (Part No. see below).

### Hand terminal

To comfortably operate the VF-CE inverters via the hand-held terminal, a protective rubber holder is included.

The keypad also allows for remote programming if the inverter is not easily accessible.

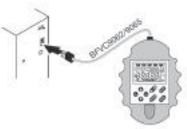
### Front panel mounting

After removing the protective rubber holder from the remote control set, the keypad can be mounted in switch-gear cabinets and operator consoles. (cut-out  $45.3 \times 45.3$ mm).

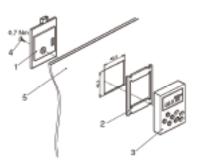
### Available cables

Part No.	Length
BFVC9062	2m
BFVC9065	5m

- 1 Baseplate
- 2 Seal
- 3 Keypad
- 4 Screw 0.7Nm
- 5 Control cabinet sheet thickness 0.5mm - 1.5mm



BFVC9060





# Specifications

Control method	V/f control (linear, square), vector control		
Operating frequency	Either 2kHz, 4kHz, 8kHz, 16kHz		
Maximum torque	$1.8 \times M_N$ for $60s$ ,		
- Waximum torque	if motor rated power = inverter rated p	ower	
Torque speed range	1:10 (3 50Hz, constant speed)		
	Min. output frequency 1.0H	z ( 0 M <sub>N</sub> ) sensorless speed control	
Sensorless speed control	Speed range 1:50	0 ( based on 50Hz)	
Sensoness speed control	Accuracy 0.5%	6 3 50Hz	
	Smooth running $\pm 0.1$	Hz 350Hz	
Generator operation	Integrated braking transistor		
(monitored internally)	integrated braking transistor		
Filter	Integrated as standard-class B		
Skip frequencies	Up to 3 skip frequencies can be set to avoid resonance		
	Motor parameter adaptation and correction, thermo-couple input for monitoring motor temperature,		
Other standard features	1ms terminal sampling time, linear and S-ramp, fixed speeds, four parameter programs can be		
	switched online, bipolar set-point proc	essing.	

# General technical data/Operating conditions

Resistance to vibration	Acceleration restistance up to 0.7g (Germanischer Lloyd, general conditions)			
Permissible temperature ranges	Storage -25°	C +70°C C +60°C C +55°C above +40	O°C the rated output current is to be reduced by 2.5%/°C	
Permissible installation height	0 4000m amsl above 1000m amsl the rated output current is to be redu 5%/1000m			
Mounting position	Vertical			
Protective measures against	Short-circuit, ground fault, over-voltage, motor becoming unstable, motor overheating (input for thermo-couple)			
Total insulation against	Safe separation from mains, double basic insulation			
control-circuits	in accordance with EN 50178			
Degree of protection	IP20			
Conformity	CE low-voltage guideline (73/23/EEC)			
Emitted interference	Requirements as per EN 50081-1 Limiting value class A as per EN 55011 Limiting value class B as per EN 55022			
	Requirements as per EN 61800-3 immunity to interference			
	Requirements	Standard	Severity	
	ESD	EN 61000-4-2	3, i.e. 8kV with air discharge 6kV with contact discharge	
Interference immunity	HF irradiation (casing)	EN 61000-4-3	3, i.e. 10V/m; 27 1000MHz	
	Colour burst	EN 61000-4-4	3/4, i.e. 2kV/5kHZ	
	Surge	EN 61000-4-5	3, i.e. 1,2/50μs, 1kV phase-phase, 2kV phase-PE	
Insulation resistance	Over-voltage category III in accordance with VDE 0110			
Approvals	UL 508 Ind	ustrial Control Equipment		
Approvais	UL 508C Pov	ver Conversion Equipment		



# Specifications

### 1-phase 230V AC

Typical Motor Power 3-phase asynchronous motor (4-pole)	P <sub>r</sub> [kW] P <sub>r</sub> [hp]	<b>0.25</b> 0.34	<b>0.37</b> 0.5	<b>0.75</b> 1.0	<b>1.5</b> 2.0	<b>2.2</b> 3.0	
VF-CE type	EMC filter integrated	BFVCE0022A	BFVCE0032A	BFVCE0072A	BFVCE0152A	BFVCE0222A	
Mains voltage	U <sub>mains</sub> [V]	1/N/PE AC 180	)V - 0 % 264V + 0 % ;	1/N/PE AC 180 V - 0 9	% 264 V + 0 % ; 45 Hz - 0 %	65 Hz + 0 %	
		45 Hz - 0	) % 65 Hz + 0 %	3/PE AC 100 V - 0% 264 V + 0%; 45 Hz - 0% 65 Hz + 0%			
Alternative DC supply	U <sub>DC</sub> [V]	n	ot possible		DC 140 V - 0% 370 V + 0%		
Data for operation with 1/N/PE or 3	/PE	1/N/PE	1/N/PE	1/N/PE 3/PE	1/N/PE 3/PE	1/N/PE <sup>5)</sup> 3/PE	
Rated mains current							
without mains choke	I <sub>mains</sub> [A]	3.4	5.0	9.0 5.2	15.0 9.1	- 12.4	
with mains choke	I <sub>mains</sub> [A]	3.0	4.2	7.5 3.6	12.5 6.3	18.0 9.0	
Output power U, V, W	S <sub>r</sub> [kVA]	0.68	1.0	1.6	2.8	3.8	
Output power +UG, -UG 1)	P <sub>DC</sub> [kW]	DC bus operation	on not possible	- 0.1	- 1.1	- 0.4	
Rated output current at chopper frequency 2kHz sin 4kHz sin	- I <sub>R</sub> [A] 4)	1.7	2.4	4.0	7.0	9.5	
8kHz sin	I <sub>R</sub> [A]	1.7	2.4	4.0	7.0	9.5	
16kHz sin <sup>3)</sup>	I <sub>R</sub> [A]	1.1	1.6	2.6	4.6	6.2	
Max. permissible 2kHz sin output current for 60s 4kHz sin	- I <sub>max</sub> [A]	2.5	3.6	6.0	10.5	14.2	
at chopper frequency <sup>2)</sup> 8kHz sin	I <sub>R</sub> [A]	2.5	3.6	6.0	10.5	14.2	
16kHz sin <sup>3)</sup>	I <sub>R</sub> [A]	1.7	2.3	3.9	6.9	9.3	
Output voltage without mains choke	U <sub>M</sub> [V]	3~ 0 Vmains / 0 650Hz					
with mains choke	U <sub>M</sub> [V]	3~ 0 approx. 94% Umains / 0 650Hz					
Power loss (operation with I <sub>r8</sub> )	UP <sub>V</sub> [W]	30 40 60 100 130		130			
Required mains choke 6)							
Rated currents	I <sub>N</sub> [A]	-	-	-	_	18.0 –	
Inductance	[mH]	-	-	-	-	2.5 –	
Dimensions	H x W x D [mm]	nm] 120x60x140 120x60x140 180x60x140 240x60x140 240x		240 x 60 x 140			
Weight	m [kg]	8.0	0.8	1.2	1.6	1.6	

Printed in bold = Data for operation at 8kHz chopper frequency (default setting)

- 1) For operation with power-adapted motors additional power to be taken from the DC bus
- 2) Currents for periodic load change: 1min overcurrent with  $\rm I_{max}$  and 2min basic load with 75 %  $\rm I_{r}$
- 3) Chopper frequency is reduced to 4kHz if  $\,\vartheta_{\mbox{\scriptsize max}}$  reaches  $5^{\circ}\mbox{\scriptsize C}$
- 4) Possible for other types with different application conditions: Operation with increased rated output current and the same load change
- 5) Operation only with mains choke
- 6) Select the mains choke for an overcurrent of 160% for at least 60s

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# Specifications

### 3-phase 400V AC

Typical Motor Power Three-phase asynchronous motor (4-pole)	P <sub>r</sub> [kW] P <sub>r</sub> [hp]	<b>0.75</b> 1.0	<b>1.5</b> 2.0	<b>2.2</b> 3.0	<b>4.0</b> 40
VF-CE type	EMC filter integrated	BFVCE0074A <sup>5)</sup>	BFVCE0154A <sup>5)</sup>	BFVCE0224A <sup>5)</sup>	BFVCE0404A
Mains voltage	U <sub>mains</sub> [V]	3/PE AC 320 V - 0 % 550 V + 0 % ; 45 Hz - 0 % 65 Hz + 0 %			
Alternative DC supply	U <sub>DC</sub> [V]	DC 450 V - 0 % 775 V + 0 %			
Data for operation with 3/PE AC 4	00V or DV 565 \	V			
Rated mains current					
without mains choke	I <sub>mains</sub> [A]	3.3	5.5	7.3	12.3
with mains choke	I <sub>mains</sub> [A]	2.3	3.9	5.1	8.8
Output power U, V, W	S <sub>r</sub> [kVA]	1.7	2.7	3.9	6.6
Output power +UG, -UG 1)	P <sub>DC</sub> [kW]	0.1	1.1	0.4	0.8
Rated output current at chopper frequency 2kHz sin 4kHz sin	I <sub>R</sub> [A] 4)	2.4	4.7	5.6	9.5
8kHz sin	I <sub>R</sub> [A]	2.4	3.9	5.6	9.5
16kHz sin <sup>3)</sup>	I <sub>R</sub> [A]	1.6	2.5	3.6	6.1
Max. permissible 2kHz sin output current for 60 s 4kHz sin	- I <sub>max</sub> [A]	3.6	5.9	8.4	14.2
at chopper frequency <sup>2)</sup> 8kHz sin	I <sub>R</sub> [A]	3.6	5.9	8.4	14.2
16kHz sin <sup>3)</sup>	I <sub>R</sub> [A]	2.4	3.8	5.5	9.1
Output voltage					
without mains choke	U <sub>M</sub> [V]	3~ 0 Vmains / 0 650 Hz			
with mains choke	U <sub>M</sub> [V]	3~ 0 approx. 94 % Umains / 0 650 Hz			
Power loss (operation with I <sub>r8</sub> )	P <sub>V</sub> [W]	60	100	130	180
Required mains choke	-	-	-	-	_
Required brake resistor 5)	Туре	BFVC9164U BFVC9165U		BFVC9165U	-
Dimensions	H x W x D [mm]	180 x 60 x 140	240 x 60 x 140	240 x 60 x 140	240 x 100 x 140
Weight	m [kg]	1.2	1.6	1.6	2.9

Printed in bold = Data for operation at 8kHz chopper frequency (default setting)

- 1) For operation with power-adapted motors additional power to be taken from the DC bus
- 2) Currents for periodic load change: 1min overcurrent with I  $_{\rm max}$  and 2 min basic load with 75% I  $_{\rm r}$
- 3) Chopper frequency is reduced to 4kHz if  $\vartheta_{\mbox{\scriptsize max}}$  reaches  $5^{\circ}\mbox{\scriptsize C}$
- Possible for other types with different application conditions:
   Operation with increased rated output current and the same load change
- 5) Operation at mains voltages 484 V 0%... 550V + 0% is only permissible with break resistor!

### **Manuals**

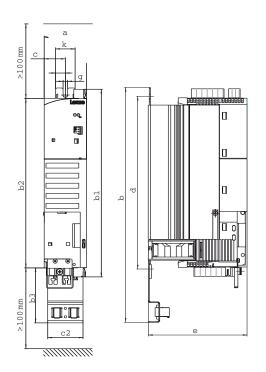
Order Number	Manual Information	Paper	PDF
ARCT1F328E	Compact Inverter VF-0 Series (1-phase, 200V) Instruction Manual		Х
ARCT1F351E	Compact Inverter VF-0 Series (3-phase, 200V) Instruction Manual		Х
ACGM0180V20EN	Inverter VF-CE COMPACT Operating Instructions	Х	
ACGM0181END	VF-CE Inverter RS232C/RS485 Communication Module Technical Specifications	Х	Х
ACGM0184END	Inverter VF-CE Compact Easy User's Guide	Х	Х
ACGM0182END	VF-CE Inverter PROFIBUS AIF Module DP Slave Operating Instructions	Х	Х
ACGM0183V20EN	VF-CE Inverter PROFIBUS FIF Module DP Slave Operating Instructions	Х	Х
VF0 Leaflet V11EN	EMC Guidelines for the VF-0 Series Inverter		Х

Paper versions can be ordered with the above product number.

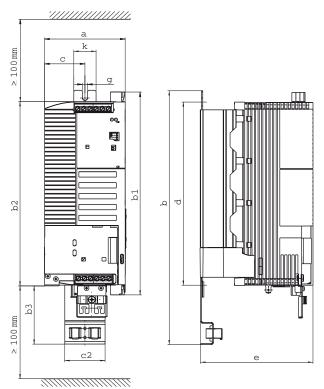
PDF versions can be downloaded from the internet free of charge: www.panasonic-electric-works.com, section motion control/inverters/manual download (New users have to register first).



# Dimensions



Dimensions in mm	BFVCE0022A BFVCE0032A	BFVCE007xA	BFVCE015xA <sup>1)</sup> BFVCE022xA <sup>1)</sup>	
а	60			
b <sup>3)</sup>	213/243/263	273/303/323	333/3592)/363	
b1	148	208	268	
b2	120	180	240	
b3	78			
С	30			
c1	63			
c2	50			
с3	130140/ 120170/ 110200/	190200/ 180230/ 170260	250260/ 280295 <sup>2</sup> / 240290	
е	140	140	100/162 <sup>2)</sup>	
g	6.5			
k	28			



BFVCE0404A			
а	100mm		
b	333mm		
b1	268mm		
b2	240mm		
b3	78mm		
С	50mm		
c1	103mm		
c2	50mm		
d	255mm		
е	140mm		
g	6.5mm		
k	28mm		

Lateral Mounting only possible with swivel mounting unit BFVE9999 with BFVCE9999
 differrent sizes depend on way of mounting using the Fixing Rails



# **Software**

# Motion Control Ver. 2.0

### The configuration software for Panasonic inverters

Motion Control is the parameter setting software from Panasonic that allows for integrated communication with all inverters which are equipped with RS232C or RS485 serial communication interfaces, including the Panasonic inverters VF-CE, VF-8E and VF-8X.

### **Functionality**

- Parameter entry
- Test operation (Start/Stop, Forward/Reverse, Acceleration/Deceleration, etc.)
- Saving and documenting settings
- Automatic drive selector
- Quick launch window
- Project navigator
- Status monitor
- Fault screen

### The Quick Launch Window

The Quick Launch Window is the starting point for the configuration environment.

### It supplies the necessary tools for:

- Creating new projects or opening projects from archives
- Setting up and establishing communication with the drive(s)
- Monitoring a drive's operation
- Sending commands to a drive
- Providing on-line help

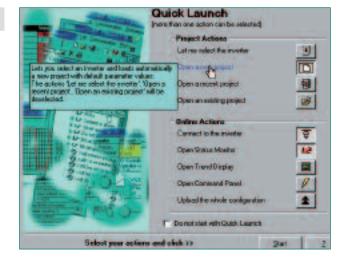
### **Project Navigator**

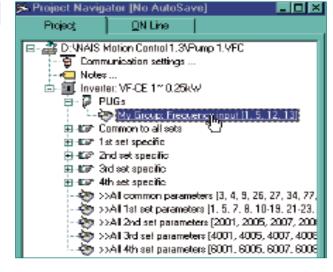
Project Navigator is the active project managment window. By double-clicking on the tree branches, it is possible to:

- Have access to the communication settings in order to establish communication with the drive(s)
- Have access to edit the parameters (parameters are grouped by common theme)
- Make one's own parameter groups with the PUG Wizard (Parameter User Groups) based on application/user needs

### Motion Control system requirements:

- Personal computer with min. 486DX4 100MHz processor and 8MB RAM (better Pentium 133MHz, 16MB RAM)
- Video card with 640x480 resolution (better 800x600)
- MS Windows 95®/98®/2000/MS Windows NT®/Windows XP
- Inverter VF-CE, VF-8E or VF-8X







# **Software**

# Motion Control Ver. 2.0

### **Editing Parameters**

The Parameter Edit windows display common groups of parameters with the default values that pertain to the selected drive. From these windows it is possible to:

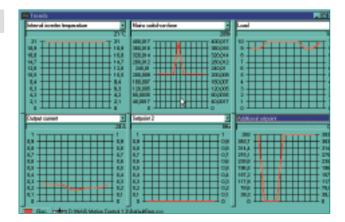
- Edit the drive(s) parameters
- Upload into one or more drives or download a set of parameters from a drive
- Start a comparison between the current project and the drive, or between two drives regarding the currently selected parameters

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### **Trend Window**

The real-time trend graphs provide constantly updated and easy-to-interpret snapshots of drive operation. They immediately show the relationship between output frequency, voltage, and current, which can be very helpful in confirming proper operation and in troubleshooting performance problems. Further parameters and values can be selected.

The Trend Window can be opened by an icon on the toolbar.

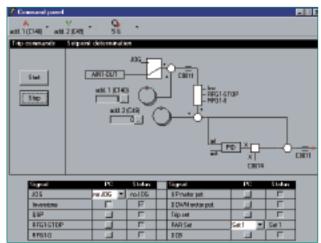


### **Command Panel**

The Command Panel allows direct control of the drive from the configuration software. From here it is possible to:

- Start and stop the drive
- Change motor direction from forward to reverse
- Control the drive's frequency setting by drag-rotation of the speed dial with the mouse pointer or by directly entering a value in the frequency display field
- Set/reset important parameters

The Command Window can be opened by an icon on the toolbar

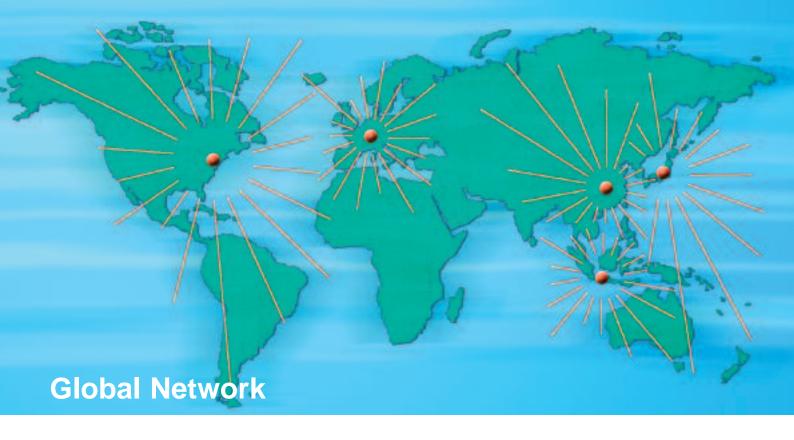


### **User Library for Control FPWIN Pro**

This library offers 20 function blocks that control the inverter series VF-CE (also the older VF-8E/8X series) via serial interfaces in the PLCs (RS232C, RS485). Typical functions include:

Starting/stopping the inverter, changing rotation direction, changing the set-point frequency, reading status information, writing parameters, etc., without detailed knowledge of the internal inverter. Product-Number: **NCL-ISC-LIBD** 

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De Rijn 4, (Postbus 211), 5684 PJ Best, (5680 AE Best), Netherlands, Tel. (0499) 372727, Fax (0499) 372185, www.panasonic-electric-works.nl Prumyslová 1, 34815 Planá, Tel. 374 799 990, Fax 374 799 999, www.panasonic-electric-works.cz

French Branch Office, B.P. 44, 91371 Verrières le Buisson CEDEX, Tél. 01 60135757, Fax 01 60135758, www.panasonic-electric-works.fr 26 Allée du Clos des Charmes, 77090 Collegien, Tél. 01 64622919, Fax 01 64622809, www.panasonic-electronic-materials.com Rudolf-Diesel-Ring 2, 83607 Holzkirchen, Tel. (08024) 648-0, Fax (08024) 648-555, www.panasonic-electric-works.de Dublin, Tel. (01) 4600969, Fax (01) 4601131, www.panasonic-electric-works.co.uk

Via del Commercio 3-5 (Z.I. Ferlina), 37012 Bussolengo (VR), Tel. (045) 6752711, Fax (045) 6700444, www.panasonic-electric-works.it Viale Elvezia 18, 20154 Milano (MI), Tel. (02) 33604525, Fax (02) 33605053, www.panasonic-building-materials.com Sjöängsvägen 10, 19272 Sollentuna, Sweden, Tel. (08) 59476680, Fax (08) 59476690, www.panasonic-electric-works.se

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### North & South America

**USA PEW Corporation of America** 629 Central Avenue, New Providence, N.J. 07974, Tel. 1-908-464-3550, Fax 1-908-464-8513, www.pewa.panasonic.com Head Office USA

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Matsushita Electric Works (China) Co., Ltd. 2013, Beijing Fortune, Building No. 5, Dong San Huan Bei Lu, Chaoyang District, Beijing, Tel. (010) 6590-8646, Fax (010) 6590-8647 Rm1601, 16/F, Tower 2, The Gateway, 25 Canton Road, Tsimshatsui, Kowloon, Hong Kong, Tel. (0852) 2956-3118, Fax (0852) 2956-0398

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